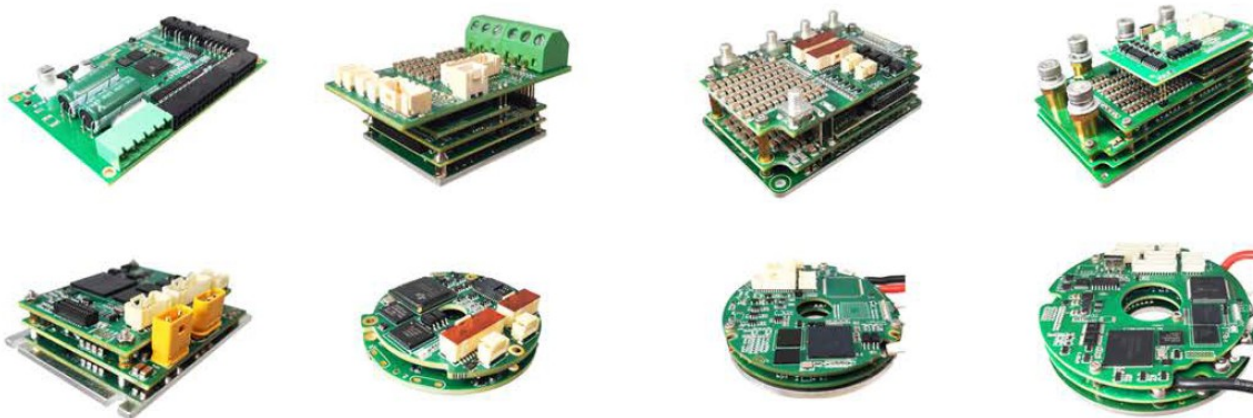




Position Control	Command Control Method			Servo enable, external reset, forward/reverse limit, motor stop, high-speed analog acquisition control, PWM synchronous signal input, high-speed pulse input
	Input Signal	Pulse Command	Input Pulse Pattern	Contains three command forms: "direction + pulse", "A, B phase orthogonal pulse", and "CW/CCW pulse"
			Signal Format	Differential input, open collector
			Maximum Pulse Frequency	Differential input (maximum 2Mpps), open collector (maximum 500Kpps)
	Analog Command	Voltage Range	Input voltage range ±10V	
		Input Impedance	Differential input impedance 5KΩ	
Speed Control	Command Control Method			PMW, ±10V analog, function generator, software programming
	Input Signal	PWM	Polarity	PWM=0-100%, Polarity=1/0
			No polarity	PMW=50%+/-50%
			Frequency Range	Min1kHz, Max100kHz
			Minimum Pulse Width	220ns
	Analog Command	Voltage Range	Input voltage range±10V	
		Input Impedance	Differential input impedance 5KΩ	
Current Control	Command Control Method			PMW, ±10V analog, function generator, software programming
	Input Signal	PWM	Polarity	PWM=0-100%, Polarity=1/0
			No polarity	PMW=50%+/-50%
			Frequency Range	Min1kHz, Max100kHz
			Minimum Pulse Width	220ns
	Analog Command	Voltage Range	Input voltage range±10V	
		Input Impedance	Differential input impedance 5KΩ	
I/O Signals	Digital Input IN	Number Of Ports		6
		Signal Format		NPN(Active low)
		Configurable Functions		Servo enable, external reset, forward/reverse limit, motor stop, high-speed analog acquisition control, PWM synchronous signal input, high-speed pulse input etc.
	Digital Output OUT	Number Of Ports		2
		Signal Format		NPN (Active low), maximum current of 800mADC, maximum voltage 30VDC
		Configurable Functions		Fault signal, brake control, program control